

Mr Donald Sammut FRCS (Plastic Surgery) - Teaching – 2019

29th -30th January 2019

Anatomy and Paralysis of the Upper limb

Lectures, instructional surgery on:

Median, Ulnar and Radial Paralysis
Anatomy dissection of the Upper limb
Extensor Tendon Anatomy
Biomechanics of the hand
Joint

Contractures, Swan Neck, Boutonniere deformities

Instructional Course for hand Surgeons and trainees; Kirtipur University Hospital, Kathmandu

27th-28th February 2019

Upper Limb Dissection Course

Vesalius Training Centre, University of Bristol, Bristol

[Flyer and information](#)

20th March 2019

Lectures to Plastic and Orthopaedic Juniors, Oxford

Median Nerve and Ulnar Nerve Paralysis:

Biomechanics, diagnosis and management

3rd April 2019



Art and Humanities Students (2nd Year Medical Students)

King's College, London

Course in 'Art of Anatomy and Surgery'

Seminar: Art in Surgery

15th May 2019

Lectures to Plastic Surgery Team Stoke Mandeville Hospital
Symposium on Work in Low Resource Communities Overseas:

***Work in low resource communities overseas:
why, how, when... and making it sustainable.***

10th June 2019



Teaching Seminar
Year 4 Medical Humanities, University of Exeter
Leprosy Surgery in India and Nepal

25th – 27th September 2019



European Course in Plastic Surgery, Oxford

Lectures on:

Biomechanics of the Hand

Tendon Transfers in the Hand



26th October 2019

Invited lectures to [Belgian Hand Therapy Society](#),
Symposium: [Nerves of the Hand](#), Van der Valk Hotel, Brussels

1. *The Anatomy of Nerve Compressions*
2. *Biomechanics of the Hand and Tendon Transfers for Hand Paralysis*

31st October – 1st November

[BSSH/IHSS Joint meeting](#)



Invited lecture:

Tendon Transfers for Median and Ulnar Paralysis: Indications and Techniques Joint meeting British and Irish Hand Societies, Dublin

16th November – 6th December 2019

Lecturing Programme:

Green Pastures Hospital, Pokhara, Nepal

Kirtipur Hospital, Kathmandu, Nepal

Programme: Anatomy; Biomechanics; clinical hand surgery